

Communicative rotary actuator with fail-safe for ball valves

- Torque motor 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative, hybrid
- Deenergised open (NO)
- Conversion of sensor signals
- Communication via BACnet MS/TP, Modbus RTU, Belimo-MP-Bus or conventional control







SRF24A-MOD-O

# **Technical data**

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Nominal voltage	AC/DC 24 V
Nominal voltage frequency	50/60 Hz
Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
Power consumption in operation	8.5 W
Power consumption in rest position	3.5 W
Power consumption for wire sizing	11 VA
Connection supply / control	Cable 1 m, 6 x 0.75 mm²
Communicative control	BACnet MS/TP

# **Data bus communication**

BACHEL WIS/ TP	
Modbus RTU (default setting)	
MP-Bus	
BACnet / Modbus see interface description	
MP-Bus max. 8	
20 Nm	

# **Functional data**

	MP-Bus max. 8
Torque motor	20 Nm
Torque fail-safe	20 Nm
Operating range Y	210 V
Operating range Y variable	0.510 V
Position feedback U	210 V
Position feedback U note	Max. 1 mA
Position feedback U variable	Start point 0.58 V End point 210 V
Position accuracy	±5%
Direction of motion motor	Y = 0 (0 V = A – AB = 0%)
Direction of motion fail-safe	Deenergised NO, valve open (A – AB = 100%)
Manual override	by means of hand crank and locking switch
Running time motor	90 s / 90°
Running time motor variable	70220 s
Running time fail-safe	<20 s @ -2050°C / <60 s @ -30°C
Adaptation setting range	manual (automatic on first power-up)
Adaptation setting range variable	No action Adaptation when switched on Adaptation after using the hand crank
Override control, controllable via bus communication	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position) = 50%
Override control variable	MAX = (MIN + 33%)100% MIN = 0%(MAX – 33%) ZS = MINMAX
Sound power level, motor	45 dB(A)
Position indication	Mechanical
Service life	Min. 60'000 fail-safe positions





# Technical data sheet

#### Safety data

Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)	
Power source UL	Class 2 Supply	
Degree of protection IEC/EN	IP54	
Degree of protection NEMA/UL	NEMA 2	
Enclosure	UL Enclosure Type 2	
EMC	CE according to 2014/30/EU	
Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14	
UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case	
Type of action	Type 1.AA	
Rated impulse voltage supply / control	0.8 kV	
Pollution degree	3	
Ambient humidity	Max. 95% RH, non-condensing	
Ambient temperature	-3050°C [-22122°F]	
Storage temperature	-4080°C [-40176°F]	
Servicing	maintenance-free	
Weight	2.2 kg	

#### Safety notes



Weight

- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or
  aggressive gases interfere directly with the device and that it is ensured that the ambient
  conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.

### **Product features**

Mode of operation

The actuator is fitted with an integrated interface for BACnet MS/TP, Modbus RTU and MP-Bus. It receives the digital control signal from the control system and returns the current status.

Converter for sensors

Connection option for a sensor (passive, active or with switching contact). In this way, the analogue sensor signal can be easily digitised and transferred to the bus systems: BACnet, Modbus or MP-Bus.

Parametrisable actuators

The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.

The communication parameters of the bus systems (address, baud rate etc.) are set with the ZTH EU. Pressing the "Address" button on the actuator while connecting the supply voltage, resets the communication parameters to the factory setting.

Quick addressing: The BACnet and Modbus address can alternatively be set using the buttons on the actuator and selecting 1...16. The value selected is added to the «Basic address» parameter and results in the effective BACnet and Modbus address.

Combination analogue - communicative (hybrid mode)

With conventional control by means of an analogue control signal, BACnet or Modbus can be used for the communicative position feedback



# **Technical data sheet**

SRF24A-MOD-O

Simple direct mounting

Simple direct mounting on the ball valve with only one screw. The mounting orientation in

relation to the ball valve can be selected in 90° steps.

Manual override By using the hand crank the valve can be operated manually and engaged with the locking

switch at any position. Unlocking is carried out manually or automatically by applying the

operating voltage.

Adjustable angle of rotation Adjustable angle of rotation with mechanical end stops.

High functional reliability The actuator is overload protected, requires no limit switches and automatically stops when the

end stop is reached.

**Home position** The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator

carries out an adaptation, which is when the operating range and position feedback adjust

themselves to the mechanical setting range.

The actuator then moves into the position defined by the control signal.

Factory setting: Y2 (counter-clockwise rotation).

Adaptation and synchronisation An adaptation can be triggered manually by pressing the "Adaptation" button or with the PC-

Tool. Both mechanical end stops are detected during the adaptation (entire setting range). Automatic synchronisation after actuating the hand crank is programmed. The synchronisation

is in the home position (0%).

A range of settings can be adapted using the PC-Tool (see MFT-P documentation)

#### **Accessories**

Tools	Description	Туре
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance	ZTH EU
	devices	MET D
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to	MFT-C ZK1-GEN
	service socket	ZKI-GEN
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN

#### **Electrical installation**



Supply from isolating transformer.

The wiring of the line for BACnet MS/TP / Modbus RTU is to be carried out in accordance with applicable RS-485 regulations.

Modbus / BACnet: Supply and communication are not galvanically isolated. Connect earth signal of the devices with one another.

Wire colours:

1 = black

2 = red

3 = white

5 = orange

6 = pink

7 = grey

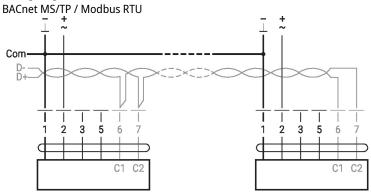
**Functions:** 

C1 = D - = A

C2 = D + = B



#### Wiring diagrams

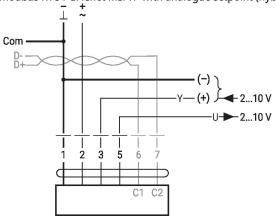


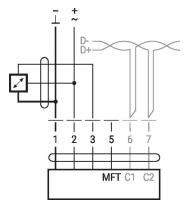
#### **Functions**

# Functions with specific parameters (Parametrisation necessary)

Modbus RTU / BACnet MS/TP with analogue setpoint (hybrid mode)

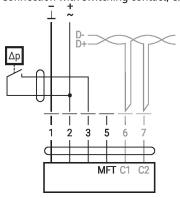
Connection with active sensor, e.g. 0...10 V @ 0...50°C





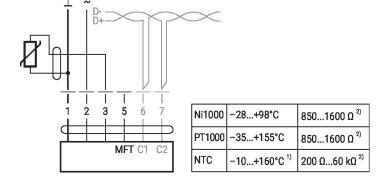
Possible input voltage range: 0...10 V Resolution 30 mV

Connection with switching contact, e.g.  $\Delta p$  monitor



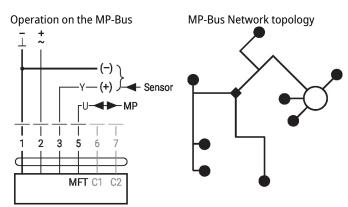
Switching contact requirements: The switching contact must be able to switch a current of 16 mA at 24 V accurately.
Start point of the operating range must be parametrised on the MOD actuator as ≥0.5 V.

Connection with passive sensor, e.g. Pt1000, Ni1000, NTC



depending on type
 Resolution 1 Ohm
 Compensation of the measured value is recommended



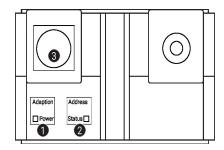


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted).

Supply and communication in one and the same 3-wire cable

- no shielding or twisting necessary
- no terminating resistors required

### Operating controls and indicators



### Membrane key and LED display green

Off: No power supply or malfunction

On: In operation

Flashing: In address mode: Pulses according to set address (1...16)

When starting: Reset to factory setting (Communication)

Press In standard mode: Triggers angle of rotation adaptation button: In address mode: Confirmation of set address (1...16)

# Membrane key and LED display yellow

Off: Standard mode

On: Adaptation or synchronisation process active

or actuator in address mode (LED display green flashing)

Flickering: BACnet / Modbus communication active

Press In operation (>3 s): Switch address mode on and off button: In address mode: Address setting by pressing several times When starting (>5 s): Reset to factory setting (Communication)

.

# Service plug

For connecting parametrisation and service tools

### **Operating elements**

The manual override, locking switch and direction of rotation switch elements are available on both sides

## Service

### **Quick addressing**

- 1. Press the "Address" button until the green "Power" LED is no longer illuminated. LED flashes in accordance with the previously set address.
- 2. Set the address by pressing the "Address" button the corresponding number of times (1...16).
- 3. The green LED flashes in accordance with the address that has been entered (...16). If the address is not correct, then this can be reset in accordance with Step 2.
- 4. Confirm the address setting by pressing the green "Adaptation" button.

If no confirmation occurs for 60 seconds, then the address procedure is ended. Any address change that has already been started will be discarded.

The resulting BACnet MS/TP and Modbus RTU address is made up of the set basic address plus the short address (e.g. 100+7=107).

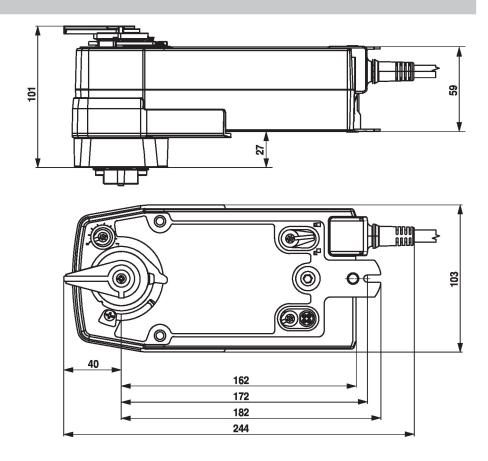


#### **Tools connection**

The actuator can be parametrised by ZTH EU via the service socket. For an extended parametrisation the PC tool can be connected.



# **Dimensions**



## **Further documentation**

- Tool connections
- BACnet Interface description
- Modbus Interface description
- Overview MP Cooperation Partners
- MP Glossary
- Introduction to MP-Bus Technology
- The complete product range for water applications
- Data sheets for ball valves
- Installation instructions for actuators and/or ball valves
- General notes for project planning